

M28V161

LOW VOLTAGE 16 Megabit (2 Meg x 8, Sector Erase) FLASH MEMORY

PRODUCT PREVIEW

- SMALL SIZE PLASTIC PACKAGES TSOP48 and SO44
- MEMORY ERASE in SECTORS
 - 32 Sectors of 64K Bytes each
- 3.3V ± 0.3V SUPPLY VOLTAGE
- 12V ± 5% PROGRAMMING VOLTAGE
- 100,000 PROGRAM/ERASE CYCLES per SECTOR
- PROGRAM/ERASE CONTROLLER
 - Program Byte-by-Byte
 - Erase by Sector, Erase Suspend/Resume Ready/Busy Output
- LOW POWER CONSUMPTION
 - 30μA Typical in Standby
 - 0.2μA Typical in Deep Power Down
- HIGH SPEED ACCESS TIME: 100ns
- EXTENDED TEMPERATURE RANGE
- COMPATIBLE to 8 MEGABIT FLASH MEMORY
 - Equal Software Command Set
 - Pinout Compatible



A0-A20	Address Inputs
DQ0-DQ7	Data Input / Outputs
Ē	Chip Enable
G	Output Enable
W	Write Enable
RP	Reset/Power Down
RY/BY	Ready/Busy Output
V _{PP}	Program & Erase Supply Voltage
Vcc	Supply Voltage
Vss	Ground

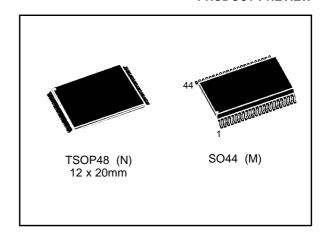
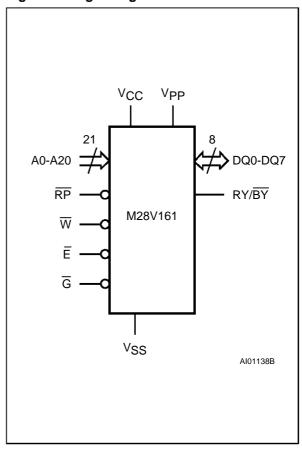
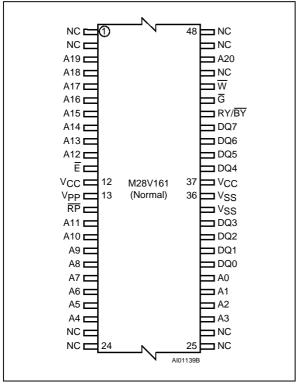


Figure 1. Logic Diagram



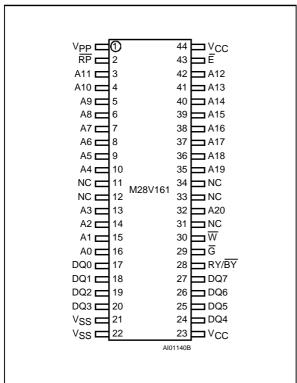
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Figure 2A. TSOP Pin Connections



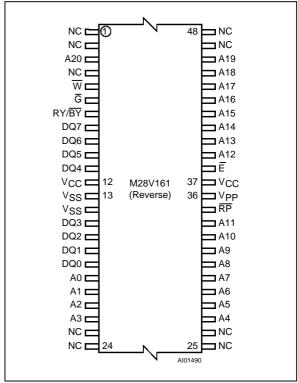
Warning: NC = Not Connected

Figure 2C. SO Pin Connections



Warning: NC = Not Connected

Figure 2B. TSOP Reverse Pin Connections



Warning: NC = Not Connected

DESCRIPTION

The M28V161 FLASH MEMORY product is a non-volatile memory that may be erased electrically at the sector level and programmed byte-by-byte. The interface is directly compatible with most microprocessors. It is intended for computer file systems and mass data storage applications. TSOP48 and S044 packages are used. The M28V161 is software and pin-out, footprint compatible with the M28F841 and M28V841, 8 Megabit FLASH Memory, with the simple addition of an address line.

Organization

The organization is 2 Meg x 8 with Address lines A0-A20 and Data Input/Outputs DQ0-DQ7. Memory control is provided by Chip Enable, Output Enable and Write Enable inputs. A Reset/Power Down input places the memory in deep power down. A Ready/Busy output indicates the status of the internal Program/Erase Controller (P/E.C.).

Sectors

Erasure of the memory is in sectors. There are 32 sectors in the memory address space, each of 64K bytes. Programming of each sector takes typically 0.6 seconds and erasure 1.6 seconds, each sector may be programmed and erased over 100,000 cycles. All sectors are protected from programming

Table 2. Absolute Maximum Ratings (1)

Symbol	Parameter	Value	Unit
TA	Ambient Operating Temperature grade 1 grade 3 grade 6	0 to 70 -40 to 125 -40 to 85	°C
T _{BIAS}	Temperature Under Bias	-50 to 125	°C
T _{STG}	Storage Temperature	-65 to 150	°C
V _{IO} (2, 3)	Input or Output Voltages	-0.6 to 5	V
V _{CC}	Supply Voltage	-0.6 to 5	V
V _{PP} ⁽²⁾	Program Supply Voltage, during Erase or Programming	-0.6 to 14	V
I _{OUT} (4)	Output Short Circuit Current	100	mA

Notes: 1. Except for the rating "Operating Temperature Range", stresses above those listed in the Table "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only and operation of the device at these or any other conditions above those indicated in the Operating sections of this specification is not implied. Exposure to Absolute Maximum Rating conditions for extended periods may affect device reliability. Refer also to the SGS-THOMSON SURE Program and other relevant quality documents

- Minimum Voltage may undershoot to -2V during transition and for less than 20ns.
 Maximum DC voltage on I/O is V_{CC} + 0.5V, overshoot to 5V allowed for less than 20ns.
- 4. Only one output shorted at a time for no longer than 1 second.

Table 3. Operations

Operation	Ē	G	w	RP	RY/BY (2)	DQ0 - DQ7
Read	V_{IL}	V _{IL}	V _{IH}	V_{IH}	V _{OH}	Data Output
Write	VIL	ViH	VIL	ViH	Vol / Voh	Data Input
Output Disable	V _{IL}	V _{IH}	V _{IH}	V _{IH}	V _{OH}	Hi-Z
Standby	V _{IH}	Х	Х	V _{IH}	V _{OH}	Hi-Z
Power Down	Х	Х	Х	VIL	V _{OH}	Hi-Z

Table 4. Electronic Signature

Code	Ē	G	w	RP	A0	RY/BY	DQ0 - DQ7
Manufact. Code	V _{IL}	V_{IL}	V _{IH}	V _{IH}	V_{IL}	V _{OH}	20h
Device Code	V _{IL}	V _{IL}	V _{IH}	V _{IH}	V _{IH}	V _{OH}	58h

DESCRIPTION (cont'd)

or erasure when the Reset/Power Down RP signal is Low. Sector erase may be suspended while data is read from other sectors of the memory, then resumed.

Bus operations

Five operations can be performed by the appropriate bus cycles, Read a Byte from the Array, Output

Disable, Standby, Power Down and Write a Command of an Instruction.

Command Interface

Commands can be written to a Command Interface (C.I.) latch to perform read, programming, erasure and to monitor then memory's status. When power is first applied, on exit from power down or if V_{CC} falls below V_{LKO}, the command interface is reset to Read Memory Array.

Notes: 1. X = V_{IL} or V_{IH}, V_{PP} = V_{PPL} or V_{PPH}
2. RY/BY = V_{OL} when the P/E.C. is executing a Sector Erase or Write operation. It is at V_{OH} when the P/E.C. is not busy, in the Erase Suspend or Power Down modes.

Table 5. Instructions

Mnemo	Instruction	Cycles		1st Cycle			2nd Cycle	
nic		Cycles	Operation	Operation Address (1) Data		Operation	Address (1)	Data
RD	Read Memory Array	1+	Write	Х	0FFh	Read ⁽²⁾	Read Address	Data Output
RSR	Read Status Register	1+	Write	Х	70h	Read ⁽²⁾	х	Status Register Output
RSIG	Read Electronic Signature	3	Write	Х	90h	Read ⁽²⁾	Signature Adress ⁽³⁾	Code Input
EE	Erase	2	Write	Х	20h	Write	Sector Address	0D0h
PG	Program	2	Write	Х	40h or 10h	Write	Address	Data Input
CLRS	Clear Status Register	1	Write	Х	50h			
ES	Erase Suspend	1	Write	Х	0B0h			
ER	Erase Resume	1	Write	Х	0D0h			

Notes: 1. X = Don't Care.

Table 6. Commands

Hex Code	Command
00h	Invalid/Reserved
10h	Alternative Program Set-up
20h	Erase Set-up
40h	Program Set-up
50h	Clear Status Register
70h	Read Status Register
90h	Read Electronic Signature
0B0h	Erase Suspend
0D0h	Erase Resume/Erase Confirm
0FFh	Read Memory Array / Reset

Instructions and Commands

Eight Instructions are defined to perform Read Memory Array, Read Status Register, Read Electronic Signature, Erase, Program, Clear Status Register, Erase Suspend and Erase Resume. An internal Program/Erase Controller handles all timing and verification of the Program and Erase instructions and provides status bits to indicate its operation and exit status. Instructions are composed of a first command write operation followed by either second command write, to confirm the commands for programming or erase, or a read operation or ead datafrom the Array, the Electronic Signature or the Status Register.

For added data protection, the instructions for byte program and sector erase consist of two commands that are written to the memory and which start the automatic P/E.C. operation. Byte programming takes typically $9\mu s$, sector erase typically 1.6 seconds. Erasure of a memory sector may be suspended in order to read data from another sector and then resumed.

^{2.} The first cycle of the RD, RSR or RSIG instruction is followed by read operations to Read Memory Array, Read Status Register or Read Electronic Signature codes. Any number or read cycles may be performed after an RD, RSR or RSIG instructions.

^{3.} Signature address bit A0=V_{IL} will output Manufacturer code. Address bit A0=V_{IH} will output Device code. Other address bits are ignored.

Table 7. Status Register

Mnemon ic	Bit	Name	Logic Level	Definition	Note
			'1'	Ready	The RY/BY output or the P/E.C. status bit may be
P/ECS	7	P/E.C. Status	'0'	Busy	checked during Program or Erase. The bit should be checked on completion before checking bits b4 or b5 for success.
		Erase	'1'	Suspended	On an Erase Suspend instruction the ESS bit is set to '1' and the P/ECS bit remains at '1'. ESS bit
ESS	6	Suspend Status	'0'	In Progress or Completed	remains '1' until an Erase Resume instruction is given.
ES	5	Erase Status	'1'	Erase Error	ES bit is set to '1' if P/E.C. has applied the
ES	5	Erase Status	'0'	Erase Success	maximum number of erase pulses to the block without achieving an erase verify.
		_	'1'	Program Error	PS bit set to '1' if the P/E.C. has failed to program a byte or word.
PS	4	Program Status	'0'	Program Success	If PS and ES bits are set to '1' during a sector erase attempt, an improper command sequence was entered and the instruction should be given again.
			'1'	V _{PP} Low, Abort	VPPS bit is set if the V _{PP} voltage is below
VPPS	3	V _{PP} Status	'0'	V _{PP} OK	V _{PPH} (min) when a Program or Erase instruction is executed and the instruction is aborted. The Status Register must be cleared before another write or erase operation is attempted.
	2	Reserved			Bits b2, b1 and b0 are reserved for future use and
	1	Reserved			should be masked out when polling the Status Register.
	0	Reserved			

Note: Logic level '1' is High, '0' is Low.

A Status Register may be read at any time, including during the programming or erase cycles, to monitor the progress of the operation. In addition a Ready/Busy output RY/BY indicates the status of the P/E.C. After Programming or Erasure the command interface must be reset by giving the Read Memory Array instruction before the memory contents can be accessed.

Power Saving

The M28V161 memory have a number of power saving features. A CMOS standby mode is entered when the Chip Enable \overline{E} and the Reset/Power Down \overline{RP} signals are at V_{CC}, when the supply current drops to typically 30 μ A. Adeep power down mode is enabled when the Reset/Power Down signal \overline{RP} is at Vss, when the supply current drops to typically 0.2 μ A. The time required to awake from the deep power down mode is 1 μ s maximum, with instructions to the C.I. recognized after 400ns.

AC MEASUREMENT CONDITIONS

 $\begin{array}{lll} \mbox{Input Rise and Fall Times} & \leq & 10 \mbox{ns} \\ \mbox{Input Pulse Voltages} & 0 \mbox{ to } 3 \mbox{V} \\ \mbox{Input and Output Timing Ref. Voltages} & 1.5 \mbox{V} \\ \end{array}$

Note that Output Hi-Z is defined as the point where data is no longer driven.

Figure 3. AC Testing Input Output Waveforms

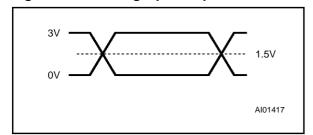


Figure 4. AC Testing Load Circuit

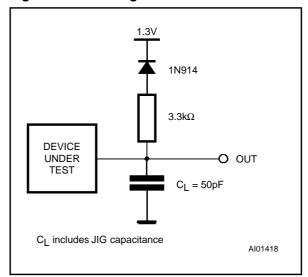


Table 8. Capacitance (1) $(T_A = 25 \, ^{\circ}C, f = 1 \, \text{MHz})$

Symbol	Parameter	Test Condition	Min	Max	Unit
C _{IN}	Input Capacitance	$V_{IN} = 0V$		8	pF
C _{OUT}	Output Capacitance	V _{OUT} = 0V		12	pF

Note: 1. Sampled only, not 100% tested.

DEVICE OPERATION

Signal Descriptions

A0-A20 Address Inputs. The address signals, inputs for the memory array, are latched during a write operation.

DQ0-DQ7 Data Input/Outputs. The data inputs, a byte to be programmed or a command to the C.I., are latched on the rising edge of Chip Enable $\overline{\mathbb{E}}$ and Write Enable $\overline{\mathbb{W}}$, whichever occurs first. The data output from the memory Array, the Electronic Signature or the Status Register is valid when Chip Enable $\overline{\mathbb{E}}$ and Output Enable $\overline{\mathbb{G}}$ are active. The output is high impedance when the chip is deselected or the outputs are disabled.

 $\overline{\mathbf{E}}$ **Chip Enable.** The Chip Enable activates the memory control logic, input buffers, decoders and sense amplifiers. $\overline{\mathbf{E}}$ High de-selects the memory and reduces the power consumption to the standby level. $\overline{\mathbf{E}}$ can also be used to control writing to the C.I. and the memory Array while $\overline{\mathbf{W}}$ remains at a low level. Both addresses and data inputs are then latched on the rising edge of $\overline{\mathbf{E}}$.

 \overline{RP} Reset/Power Down. This input allows the memory to be placed in a deep power down mode. If \overline{RP} is within $V_{SS}\pm0.2V$ the lowest supply current is absorbed.

RY/BY Read/Busy. This output indicates when the Program Erase Controller is executing a program or erase. It is always active, even during power down. If RY/BY is at V_{OL}, the P/E.C. is active.

G Output Enable. The Output Enable gates the outputs through the data buffers during a read operation.

W Write Enable. This controls writing to the C.I., Address and Input Data latches. Both Addresses and Input Data are latched on the rising edge of W.

VPP Program Supply Voltage. This supply voltage is used for memory Programming and Erase.

Vcc Supply Voltage. This is the main circuit supply.

V_{SS} **Ground.** This is the reference for all the voltage measurements.



Table 9. DC Characteristics

(T_A = 0 to 70 °C, -40 to 85 °C or -40 to 125 °C; V_{CC} = 3.3V \pm 0.3V; V_{PP} = 12V \pm 5%)

Symbol	Parameter	Test Condition	Min	Max	Unit
ILI	Input Leakage Current	$0V \le V_{IN} \le V_{CC}$		±1	μΑ
I _{LO}	Output Leakage Current	0V ≤ V _{OUT} ≤ V _{CC}		±10	μΑ
Icc (1, 3)	Supply Current (Read) TTL	$\overline{E} = V_{IL}, \overline{G} = V_{IL}, f = 8MHz$		30	mA
100	Supply Current (Read) CMOS	$\overline{E} = V_{SS}, \overline{G} = V_{SS}, f = 8MHz$		20	mA
. (1.3)	Supply Current (Standby) TTL	$\overline{E} = V_{IH}, \overline{RP} = V_{IH}$		1	mA
I _{CC1} ^(1, 3)	Supply Current (Standby) CMOS	$\frac{\overline{E} = V_{CC} \pm 0.2V,}{\overline{RP} = V_{CC} \pm 0.2V}$		100	μΑ
I _{CC2} ^(1, 3)	Supply Current (Power Down)	$\overline{RP} = V_{SS} \pm 0.2V$		5	μΑ
Icc3 (1, 3)	Supply Current (Program)	Byte program in progress		30	mA
I _{CC4} (1, 3)	Supply Current (Erase)	Sector Erase in progress		30	mA
I _{CC5} (1, 2, 3)	Supply Current (Erase Suspend)	\overline{E} = V _{IH} , Erase suspended		6	mA
I _{PP}	Program Current (Read)	V _{PP} > V _{CC}		200	μΑ
I _{PP1}	Program Current (Standby)	$V_{PP} \leq V_{CC}$		±10	μΑ
I _{PP2}	Program Current (Power Down)	$\overline{RP} = V_{SS} \pm 0.2V$		5	μΑ
I _{PP3}	Program Current (Program)	Byte program in progress		15	mA
I _{PP4}	Program Current (Erase)	Sector Erase in progress		10	mA
I _{PP5}	Program Current (Erase Suspend)	Erase suspended		200	μΑ
V _{IL}	Input Low Voltage		-0.5	0.8	V
ViH	Input High Voltage		2	V _{CC} + 0.3	V
V _{OL}	Output Low Voltage	I _{OL} = 2mA		0.4	V
VoH	Output High Voltage	I _{OH} = -2mA	2.4		V
V _{PPL}	Program Voltage (Normal operation)		0	V _{CC} + 0.3	٧
V _{PPH}	Program Voltage (Program or Erase operations)		11.4	12.6	V
V _{LKO}	Supply Voltage (Program or Erase Lock-out)		2		V

Memory Sectors

There are 32, 64K Byte memory sectors. Each sector of the memory can be erased separately, but only one sector at a time. The erase operation is managed by the P/E.C. but can be suspended in order to read from another sector and then resumed.

Programming and erasure of the memory is disabled when the Program Supply Voltage is at VPPL. For successful programming and erasure the Program Supply Voltage must be at VPPH throughout the operation.

Notes: 1. Supply Current specified with I_{OUT} (RY/ \overline{PY}) = 0. 2. Current increases to I_{CC} + I_{CCS} during a read operation with erase suspended. 3. CMOS levels V_{CC} ± 0.2V and V_{SS} ± 0.2V. TTL levels V_{IH} and V_{IL} .

Table 10. Read AC Characteristics

 $(T_A = 0 \text{ to } 70^{\circ}\text{C}, -40 \text{ to } 85^{\circ}\text{C} \text{ or } -40 \text{ to } 125^{\circ}\text{C}; V_{CC} = 3.3\text{V} \pm 0.3\text{V}; V_{PP} = 12\text{V} \pm 5\%)$

						M28	V161			
Symbol	Alt	Parameter	Test Condition	-1	00	-1.	20	-1	50	Unit
				Min	Max	Min	Max	Min	Max	
t _{AVAV}	t _{RC}	Address Valid to Next Address Valid	$\overline{E} = V_{IL}, \overline{G} = V_{IL}$	100		120		150		ns
t _{AVQV}	t _{ACC}	Address Valid to Output Valid	$\overline{E} = V_{IL}, \ \overline{G} = V_{IL}$		100		120		150	ns
t _{PHQV}	t _{PWH}	Power Down High to Output Valid	$\overline{E} = V_{IL}, \ \overline{G} = V_{IL}$		1		1		1	μs
t _{ELQX} (1)	t _{LZ}	Chip Enable Low to Output Transition	$\overline{G} = V_{IL}$	0		0		0		ns
t _{ELQV} (2)	t _{CE}	Chip Enable Low to Output Valid	$\overline{G} = V_{IL}$		100		120		150	ns
t _{GLQX} (1)	toLZ	Output Enable Low to Output Transition	E = V _{IL}	0		0		0		ns
t _{GLQV} (2)	t _{OE}	Output Enable Low to Output Valid	E = V _{IL}		45		50		50	ns
t _{EHQX}	tон	Output Enable High to Output Transition	G = V _{IL}	0		0		0		ns
t _{EHQZ} (1)	t _{HZ}	Chip Enable High to Output Hi-Z	$\overline{G} = V_{IL}$		50		50		55	ns
t _{GHQX}	tон	Output Enable High to Output Transition	E = V _{IL}	0		0		0		ns
t _{GHQZ} (1)	t _{DF}	Output Enable High to Output Hi-Z	E = V _{IL}		30		40		50	ns
t _{AXQX}	tон	Address Transition to Output Transition	$\overline{E} = V_{IL}, \overline{G} = V_{IL}$	0		0		0		ns

Notes: 1. Sampled only, not 100% tested.
2. G may be delayed by up to telay - tglay after the falling edge of E without increasing telay.

Operations

Operations are defined as specific bus cycles and signals which allow memory Read, Command Write, Output Disable, Standby, Power Down and Electronic Signature Read. They are shown in Table 3.

Read. Read operations are used to output the contents of the Memory Array, the Status Register or the Electronic Signature. Both Chip Enable E and Output Enable G must be Low in order to read the output of the memory. The Chip Enable input also provides power control and should be used for device selection. Output Enable should be used to gate data onto the output independent of the device selection. A read operation will output a byte on DQ0-DQ7.

The data read depends on the previous command written to the C.I. (see instructions RD, RSR and RSIG).

Write. Write operations are used to give Instruction Commands to the memory or to latch input data to be programmed. A write operation is initiated when Chip Enable E is Low and Write Enable W is Low with Output Enable G High. Commands, Input Data and Addresses are latched on the rising edge of \overline{W} or E. As for read operations data is transferred on DQ0-DQ7.

Output Disable. The data outputs are high impedance when the Output Enable G is High with Write Enable W High.



Figure 5. Read Mode AC Waveforms

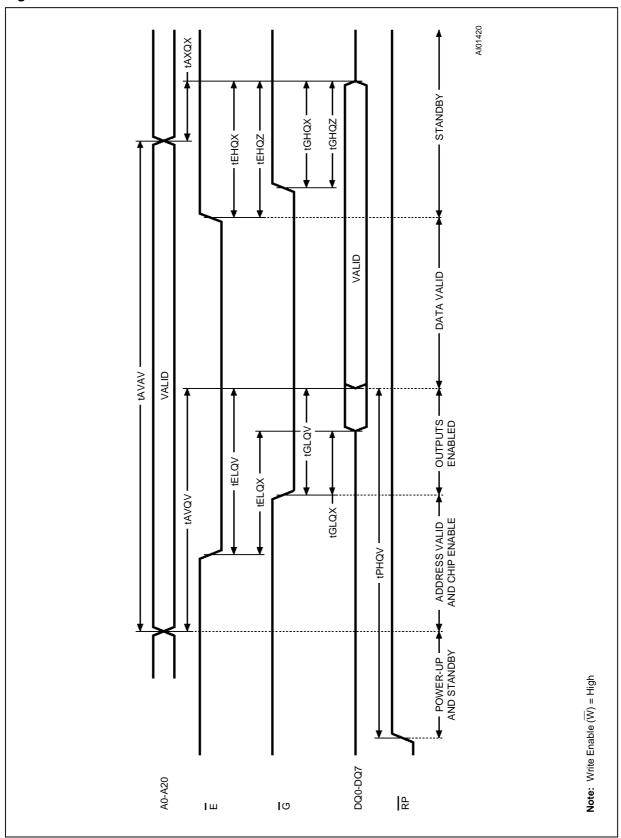


Table 11. Byte Program, Erase Time

 $(T_A = 0 \text{ to } 70^{\circ}\text{C}, -40 \text{ to } 85^{\circ}\text{C} \text{ or } -40 \text{ to } 125^{\circ}\text{C}; V_{CC} = 3.3\text{V} \pm 0.3\text{V})$

Parameter	Test Conditions		M28V161		Unit
radineter	rest conditions	Min	Тур	Max	Oint
Sector Program	V _{PP} = 12V ± 5%		0.6	2.1	sec
Sector Erase	$V_{PP} = 12V \pm 5\%$		1.6	10	sec

Table 12. Write AC Characteristics, Write Enable Controlled

 $(T_A = 0 \text{ to } 70^{\circ}\text{C}, -40 \text{ to } 85^{\circ}\text{C} \text{ or } -40 \text{ to } 125^{\circ}\text{C}; V_{CC} = 3.3\text{V} \pm 0.3\text{V}; V_{PP} = 12\text{V} \pm 5\%)$

			M28V161						Unit
Symbol	Alt	Parameter		-100		20	-1:	50	Oille
			Min	Max	Min	Max	Min	Max	
t _{AVAV}	twc	Write Cycle Time	100		120		150		ns
t _{PHWL} (1)	t _{PS}	Power Down High to Write Enable Low	1		1		1		μs
t _{ELWL}	t _{CS}	Chip Enable Low to Write Enable Low	0		0		0		ns
t _{WLWX}	twp	Write Enable Low to Write Enable Transition	40		40		40		ns
t _{DVWH}	t _{DS}	Input Valid to Write Enable High	40		40		40		ns
t _{WHDX}	t _{DH}	Write Enable High to Input Transition	5		5		5		ns
t _{WHEH}	tсн	Write Enable High to Chip Enable High	10		10		10		ns
t _{WHWX}	t _{WPH}	Write Enable High to Write Enable Transition	30		30		30		ns
tavwh	t _{AS}	Address Valid to Write Enable High	40		40		40		ns
t _{VPHWH} (1)	t _{VPS}	V _{PP} High to Write Enable High	100		100		100		ns
twhax	t _{AH}	Write Enable High to Address Transition	5		5		5		ns
t _{WHGL}		Write Enable High to Output Enable Low	0		0		0		ns
twhrl		Write Enable High to Ready Busy Low		100		100		100	ns
t _{WHQV1} (2)		Write Enable High to Output Valid (Byte Program)	6		6		6		μs
t _{WHQV2} (2, 3)		Write Enable High to Output Valid (Sector Erase)	0.3		0.3		0.3		sec
t _{QVVPX} (1, 2)	t∨PH	Output Valid or Ready Busy High to V _{PP} Transition	0		0		0		ns



Notes: 1. Sampled only, not 100% tested.

2. Byte Program and Sector Erase durations are measured to completion as indicated by Status Register b7 = 1 or RY/BY = high.

VPP is held high until Status Register bits b3, b4 and b5 indicate Program or Sector Erase success.

3. Temperature range 0 to 70 °C (grade 1) only.

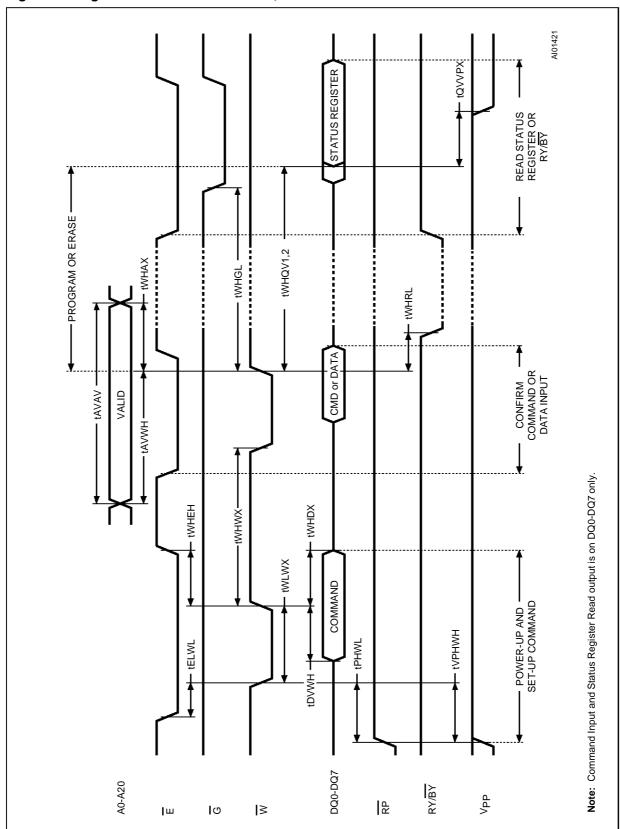


Figure 6. Program & Erase AC Waveforms, W Controlled

Table 13. Write AC Characteristics, Chip Enable Controlled (TA = 0 to 70 °C, -40 to 85 °C or -40 to 125 °C; V_{CC} = 3.3V \pm 0.3V; V_{PP} = 12V \pm 5%)

			M28V161						Unit
Symbol	Alt	Parameter	-100		-1:	20	0 -150		Onit
			Min	Max	Min	Max	Min	Max	
tavav	twc	Write Cycle Time	100		120		150		ns
t _{PHEL} (1)	t _{PS}	Power Down High to Chip Enable Low	1		1		1		μs
t _{WLEL}	t _{WS}	Write Enable Low to Chip Enable Low	0		0		0		ns
t _{ELEX}	t _{CP}	Chip Enable Low to Chip Enable Transition	50		50		50		ns
t _{DVEH}	t _{DS}	Input Valid to Chip Enable High	40		40		40		ns
t _{EHDX}	t _{DH}	Chip Enable High to Input Transition	5		5		5		ns
tенwн	t _{CH}	Chip Enable High to Write Enable High	5		5		5		ns
t _{EHEX}	t _{EPH}	Chip Enable High to Chip Enable Transition	25		25		25		ns
t _{AVEH}	t _{AS}	Address Valid to Chip Enable High	40		40		40		ns
t _{VPHEH} (1)	t _{VPS}	V _{PP} High to Chip Enable High	100		100		100		ns
t _{EHAX}	t _{AH}	Chip Enable High to Address Transition	5		5		5		ns
t _{EHGL}		Chip Enable High to Output Enable Low	0		0		0		ns
t _{EHRL}		Chip Enable High to Ready Busy Low		100		100		100	ns
tehQV1 (2)		Chip Enable High to Output Valid (Byte Program)	6		6		6		μs
t _{EHQV2} (2, 3)		Chip Enable High to Output Valid (Sector Erase)	0.3		0.3		0.3		sec
t _{QVVPX} (1, 2)	t _{∨PH}	Output Valid or Ready Busy High to V _{PP} Transition	0		0		0		ns

Notes: 1. Sampled only, not 100% tested.

2. Byte Program and Sector Erase durations are measured to completion as indicated by Status Register b7 = 1 or RY/BY = high.

VPP is held high until Status Register bits b3, b4 and b5 indicate Program or Sector Erase success.

3. Temperature range 0 to 70 °C (grade 1) only.

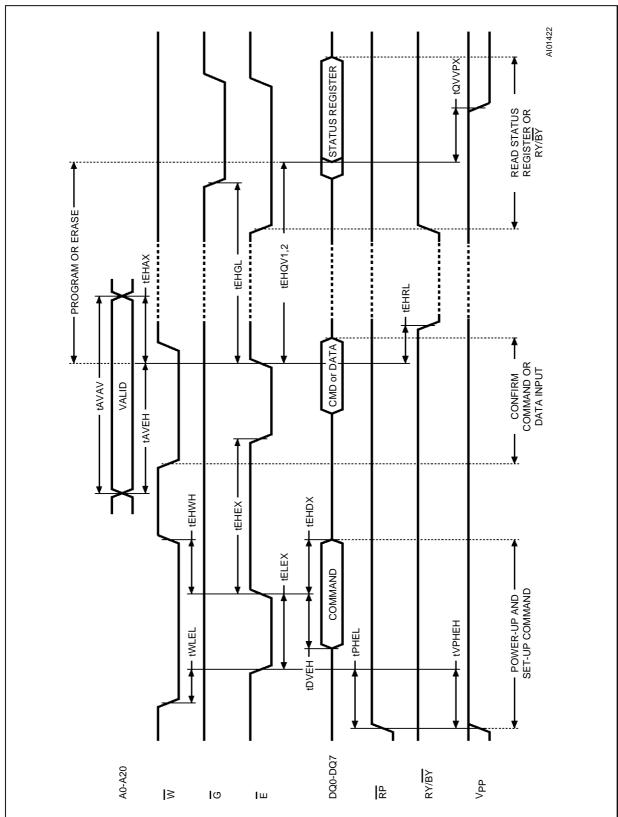


Figure 7. Program & Erase AC Waveforms, E Controlled

Figure 8. Memory Map, Byte-wide Addresses

TOP ADDRESS		BOTTOM ADDRESS
A0-A20		A0-A20
1FFFFFh	64K BYTE SECTOR	1F0000h
1EFFFFh	64K BYTE SECTOR	
1DFFFFh	64K BYTE SECTOR	1E0000h 1D0000h
1CFFFFh	64K BYTE SECTOR	
1BFFFFh		1C0000h
1AFFFFh		1B0000h
19FFFFh		1A0000h
18FFFFh		190000h
17FFFFh		180000h
16FFFFh		170000h
15FFFFh		160000h
14FFFFh		150000h
13FFFFh		140000h
12FFFFh		130000h
11FFFFh		120000h
10FFFFh		110000h
0FFFFFh		100000h
0EFFFFh		0F0000h
0DFFFFh		0E0000h 0D0000h
0CFFFFh		0C0000h
0BFFFFh		0B0000h
0AFFFFh		
9FFFFh		0A0000h 90000h
8FFFFh		80000h
7FFFFh		70000h
6FFFFh		
5FFFFh		60000h
4FFFFh		50000h
3FFFFh	64K BYTE SECTOR	40000h
2FFFFh	64K BYTE SECTOR	30000h 20000h
1FFFFh	64K BYTE SECTOR	
0FFFFh	64K BYTE SECTOR	10000h 00000h

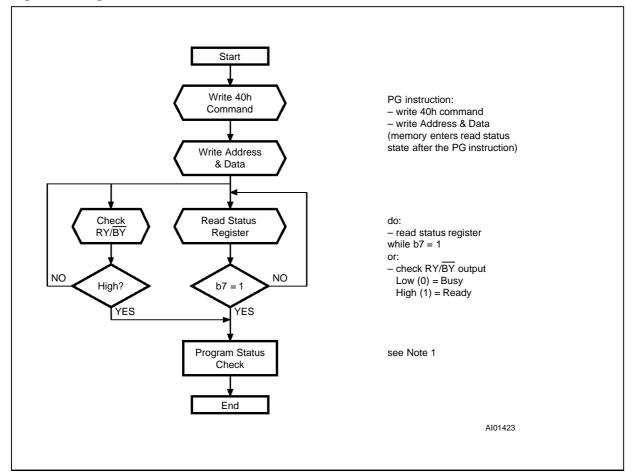


Figure 9. Program Flow-chart and Pseudo Code

Note: 1. Status check of b7 can be made after each byte programming or after a sequence.

Standby. The memory is in standby when the Chip Enable \bar{E} is High. The power consumption is reduced to the standby level and the outputs are high impedance, independent of the Output Enable \bar{G} or Write Enable \bar{W} inputs.

Power Down. The memory is in Power Down when RP is Low. The power consumption is reduced to the power down level and the outputs are high impedance independent of the Chip Enable E, Output Enable G or Write Enable W inputs.

Electronic Signature. Two codes identifying the manufacturer and the device can be read from the memory, the manufacturer code for SGS-THOMSON is 20h and the device code for the M28V161 is 58h. These codes allow applications to match their interfaces to the characteristics of the particular manufacturer's product.

The two Electronic Signature codes are output by a read operations with the Address line A0 at V_{IL} or V_{IH} , following an instruction RSIG to the memory.

Instructions and Commands

The memory includes a Command Interface (C.I.) which latches commands written to the memory. Instructions are made up from one or more commands to perform memory Read, Read Status Register, Read Electronic Signature, Erase, Program, Clear Status Register, Erase Suspend and Erase Resume. These instructions require from one to 3 operations, the first of which is always a write operation followed by either a further write operation to input address and data or to confirm the command, or a read operation to output data.

A Status Register indicates the P/E.C. status Ready/Busy, the suspend/in-progress status of

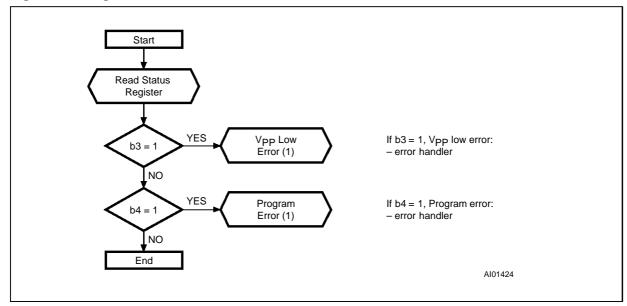


Figure 10. Program Status Check Flow-chart and Pseudo Code

Note: 1. If a V_{PP} Low or Program error is found, the Status Register must be cleared (CLRS instruction) before further P/E.C. operations.

DEVICE OPERATION (cont'd)

erase operations, the failure/success of erase and program operations and the low/correct value of the V_{PP} Program Supply Voltage.

The P/E.C. sets status bits b3 to b7 and clears bit b6 & b7. It cannot clear bits b3 to b5. The status register can be read by the Read Status Register RSR instruction and cleared by the Clear Status Register CLRS instruction. The meaning of the register bits b3 to b7 is shown in Table 7. Bit b0 to b2 are reserved for future use and should be masked out during status checks.

The P/E.C. Ready/Busy status is also indicated by the RY/BY output.

Read (RD) instruction. The Read instruction consists of one write operation giving the command 0FFh. Subsequent read operations will read data from the addressed byte of the memory array, until a new command is written to the C.I.

Read Status Register (RSR) instruction. The Read Status Register instruction may be given at any time, including while the Program/Erase Controller is active. It consists of one write operation giving the command 70h. Subsequent read operations output the contents of the status register. The contents are latched on the falling edge of \overline{E} or \overline{G} signals, and can be read until \overline{E} or \overline{G} returns to its initial high level. Either \overline{E} or \overline{G} must be toggled to V_{IH} to update the latch. Additionally, any read attempt during program or erase operation will automatically output the contents of the status register.

Read Electronic Signature (RSIG) instruction.

This instruction uses 3 operations. It consists of one write operation giving the command 90h, followed by two read operations to output the manufacturer and device codes. The manufacturer code is output when the address line A0 is Low and the device code when A0 is High.

Erase (EE) instruction. The memory can be erased in sectors. The Program Supply Voltage V_{PPH} must be applied before the Erase (EE) instruction is given. This instruction uses two write operations. The first command written is the Erase Set-up command 20h. The second is the Erase Confirm command 0D0h. During the input of the second command an address within the sector to be erased is given and this is latched into the memory. If the second command given is not the Erase Confirm command then the status register bits b4 & b5 are set and the instruction aborts. Read operations output the status register after erasure has started.

During the execution of the erase by the P/E.C., the memory accepts only the Read Status Register (RSR) or Erase Suspend (ES) instructions. Status Register bit b7 returns '0' while the erasure is in progress and '1' when it is completed. After completion the Status Register bit b5 returns '1' if there has been an erase failure because erasure has not been verified after even the maximum number of erase pulses have been given. The Status Register bit b3 returns '1' if the Program Supply Voltage V_{PP} does not remain at V_{PPH} when erasure is attempted and/or proceeding.

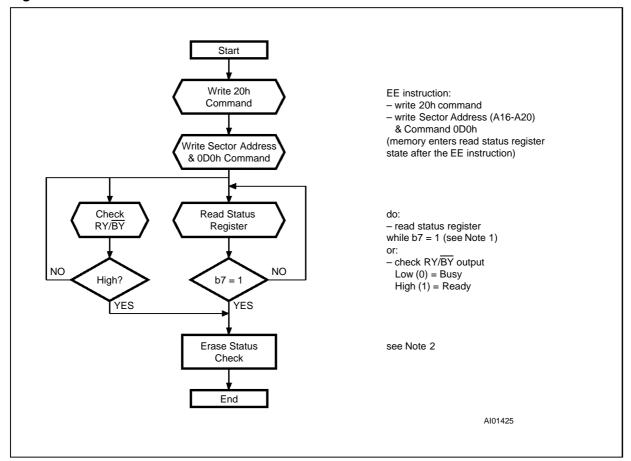


Figure 11. Erase Flow-chart and Pseudo Code

Notes: 1. An Erase Suspend may be executed during this loop.

2. See separate flow-chart.

 V_{PP} must be at V_{PPH} when erasing. Erase should not be attempted when $V_{PP} < V_{PPH}$ as the results will be uncertain. If V_{PP} falls below V_{PPH} or if \overline{RP} goes Low the erase aborts and must be repeated, after having cleared the Status Register with the CLRS instruction.

The execution of the erase by the P/E.C. is also indicated by the RY/BY output.

A full status check can be made after sector erase. The status check is made on the Status Register bit b3 for any possible VPP error, on bit b5 for an erase error or on both bits b4 & b5 for a command sequence error.

Program (PG) instruction. The memory is programmed byte-by-byte. The Program Supply Voltage V_{PPH} must be applied before the Program (PG) instruction is given and may be applied continuously during programming of a sequence of bytes. This instruction uses two write operations. The first

command written is the Program Set-up command 40h (or alternatively 10h). A second write operation latches the address and input data and starts the P/E.C. execution. Read operations output the Status Register after programming has started.

Memory programming is only made by writing a '0' in place of a '1' in a byte. To write a '1' in place of a '0' the Sector must first be erased to all '1's.

During the execution of the programming the memory accepts only the Read Status Register (RSR) instruction. The Status Register bit b7 returns '0' while programming is in progress and '1' when it is completed. After completion the Status Register bit b4 returns '1' if there has been a program failure. Status Register bit b3 returns a '1' if the Program Supply Voltage VPP does not remain at VPPH when programming is attempted and/or during programming.

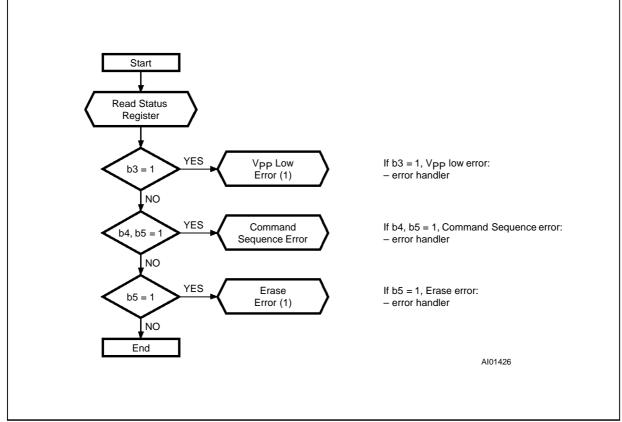


Figure 12. Erase Status Check Flow-chart and Pseudo Code

Note: 1. If VPP Low or Erase error is found, the Status Register must be cleared (CLRS instruction) before further P/E.C. operations.

DEVICE OPERATION (cont'd)

 V_{PP} must be at V_{PPH} when programming. Programming should not be attempted when $V_{PP} < V_{PPH}$ as the results will be uncertain. Programming aborts if V_{PP} drops below V_{PPH} or \overline{RP} goes Low. If aborted the data may be incorrect, the Status Register must be cleared with the Clear Status Register (CLRS) instruction, the sector erased and reprogrammed.

The execution of the programming by the P/E.C. is also indicated by the RY/BY output.

A full status check can be made after each byte or after a sequence of bytes has been programmed. The status check is made on the Status Register bit b3 for any possible VPP error and on bit b4 for a programming error.

Clear Status Register (CLRS) instruction. This instruction uses a single write operation which clears the Status Register bits b3, b4 & b5 to '0'. The CLRS instruction reverts the device to the Read Array mode and is used before any new

operation when errors have been detected during programming or erasure.

Erase Suspend (ES) instruction. An Erase operation may be suspended by using this instruction which consists of writing the command 0B0h. The Status Register bit b6 indicates wether the P/E.C. is suspended, bit b6 = '1', or whether the P/E.C. cycle was the last and the erase is complete, bit b6 = '0'. During suspension the memory will respond only to Read (RD), Read Status Register (RSR) or Erase Resume (ER) instructions. Immediately following the ES instruction, read operations initially output the contents of the Status Register while erase is suspended, but if a Read (RD) instruction is given data may be read from other sectors of the memory. The Program Supply Voltage VPP must be maintained at VPPH while erase is suspended. If V_{PP} does not remain at V_{PPH} or if the \overline{RP} input goes Low, the erase operation is aborted and Status Register bits b3 & b5 are set. In this case the Status Register must be cleared and the erase operation repeated to be certain to erase the sector.

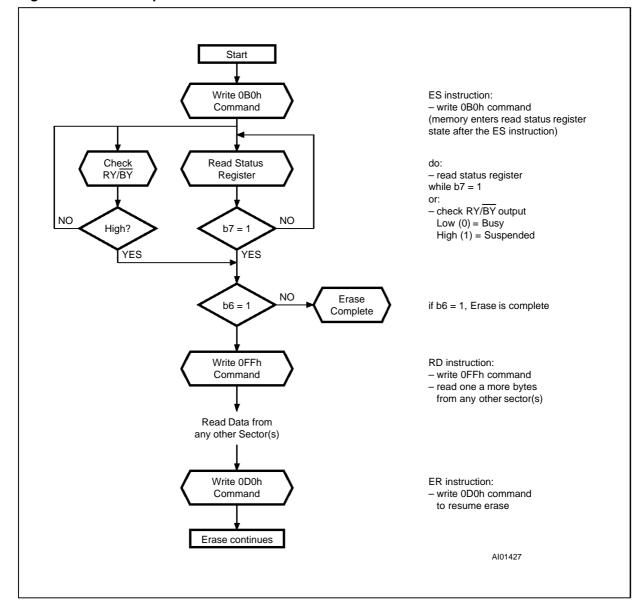


Figure 13. Erase Suspend & Resume Flow-chart and Pseudo Code

Erase Resume (ER) instruction. If an Erase Suspend instruction has been previously executed, the erase operation may be resumed giving the command 0D0h. The Status Register bit b6 will be cleared when erase resumes. Read operations output the Status Register after the erase is resumed.

Reset. After any error has occurred during programming or erase the Status Register must be cleared by giving the Clear Status Register instruction before the memory array may be read.

After a successful program or erase operation either the Read or Clear Status Register instruction must be given before the memory array may be read.

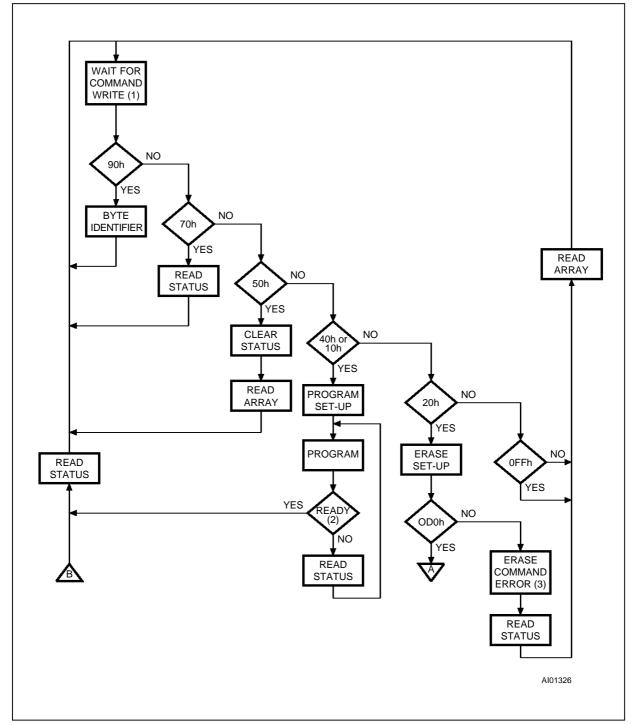


Figure 14. Command Interface and Program Erase Controller Flow-diagram (a)

Notes: 1. If no command is written, the Command Interface remains in its previous valid state. Upon power-up, on exit from power-down or if V_{CC} falls below V_{LKO}, the Command Interface defaults to Read Array mode.

2. P/E.C. status (Ready or Busy) is read on Status Register bit 7.

3. Upon Erase command error, the P/E.C. defaults to Read status and sets bits b4 and b5 of the Status Register. Program and Erase

commands will be accepted only after the Status Register has been reset by a CLRS command.

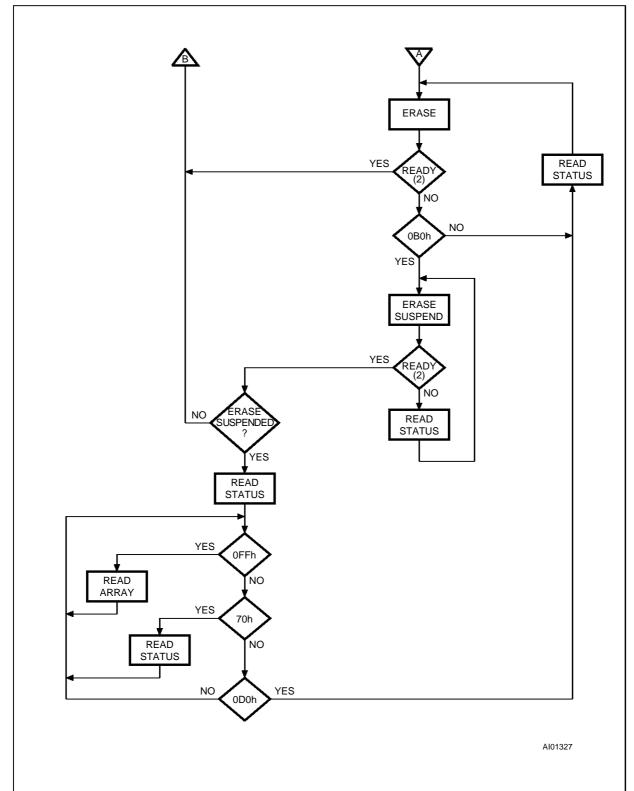
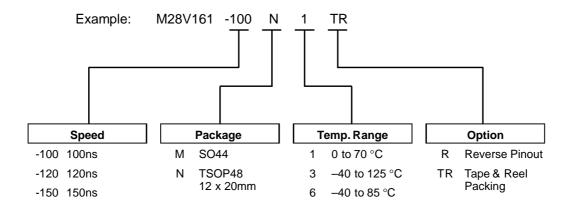


Figure 15. Command Interface and Program Erase Controller Flow-diagram (b)

Note: 2. P/E.C. status (Ready or Busy) is read on Status Register bit 7.

ORDERING INFORMATION SCHEME



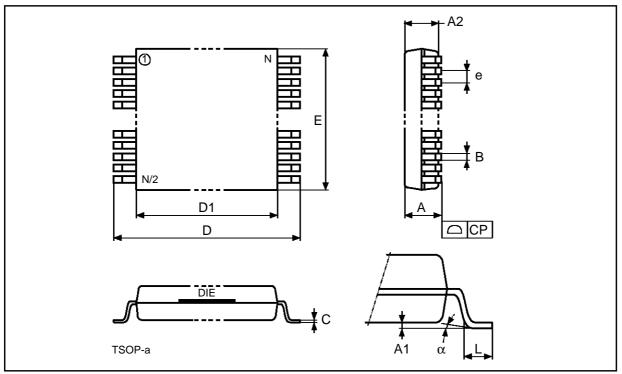
For a list of available options (V_{CC} Range, Array Organisation, Speed, etc...) refer to the current Memory Shortform catalogue.

For further information on any aspect of this device, please contact SGS-THOMSON Sales Office nearest to you.

TSOP48 Normal Pinout - 48 lead Plastic Thin Small Outline, 12 x 20mm

Symb	mm			inches			
	Тур	Min	Max	Тур	Min	Max	
А			1.20			0.047	
A1		0.05	0.15		0.002	0.006	
A2		0.95	1.05		0.037	0.041	
В		0.17	0.27		0.007	0.011	
С		0.10	0.21		0.004	0.008	
D		19.80	20.20		0.780	0.795	
D1		18.30	18.50		0.720	0.728	
Е		11.90	12.10		0.469	0.476	
е	0.50	_	_	0.020	_	_	
L		0.50	0.70		0.020	0.028	
α		0°	5°		0°	5°	
N	48			48			
СР			0.10			0.004	

TSOP48

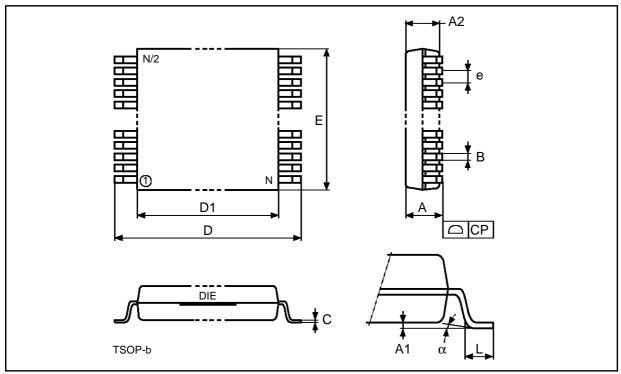


Drawing is not to scale

TSOP48 Reverse Pinout - 48 lead Plastic Thin Small Outline, 12 x 20mm

Symb	mm			inches			
	Тур	Min	Max	Тур	Min	Max	
А			1.20			0.047	
A1		0.05	0.15		0.002	0.006	
A2		0.95	1.05		0.037	0.041	
В		0.17	0.27		0.007	0.011	
С		0.10	0.21		0.004	0.008	
D		19.80	20.20		0.780	0.795	
D1		18.30	18.50		0.720	0.728	
Е		11.90	12.10		0.469	0.476	
е	0.50	_	_	0.020	_	_	
L		0.50	0.70		0.020	0.028	
α		0°	5°		0°	5°	
N		48			48		
СР			0.10			0.004	

TSOP48



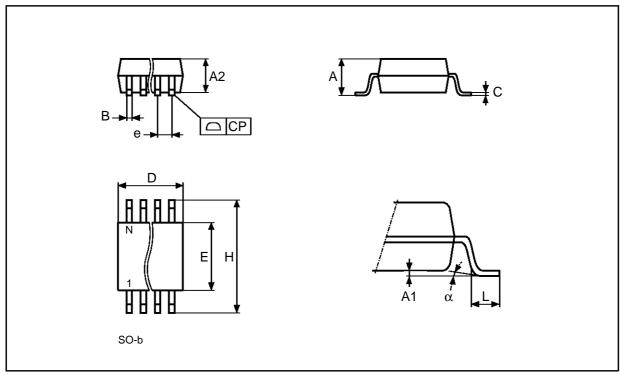
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SGS-THOMSON MICROELECTRONICS

SO44 - 44 lead Plastic Small Outline, 525 mils body width

Symb		mm		inches			
	Тур	Min	Max	Тур	Min	Max	
Α		2.42	2.62		0.095	0.103	
A1		0.22	0.23		0.009	0.010	
A2		2.25	2.35		0.089	0.093	
В			0.50			0.020	
С		0.10	0.25		0.004	0.010	
D		28.10	28.30		1.106	1.114	
Е		13.20	13.40		0.520	0.528	
е	1.27	_	_	0.050	_	_	
Н		15.90	16.10		0.626	0.634	
L	0.80	_	_	0.031	_	_	
α	3°	_	_	3°	_	_	
N		44			44		
СР			0.10			0.004	

SO44



Drawing is not to scale

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